



Detect & Avoid Alerting Logic for Unmanned Systems¹

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NASA Langley Formal Methods work in support of the NASA
UAS in the NAS Project

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¹This working document contains information that is publicly available (see references). The DAIDALUS logo was designed by M. Malekpour.

What's in a Name?

- ▶ DAIDALUS is a reference to the craftsman of Greek mythology, *Daedalus*, the father of Icarus.
- ▶ **Daedalus** made wings for himself and for Icarus and **warned Icarus not to fly too high**, because the heat of the sun would melt the wax, **nor too low**, because the sea foam would soak the feathers.



²Image taken from <http://en.wikipedia.org/wiki/Daedalus>.

DAIDALUS

Detect and Avoid Alerting Logic for Unmanned Systems

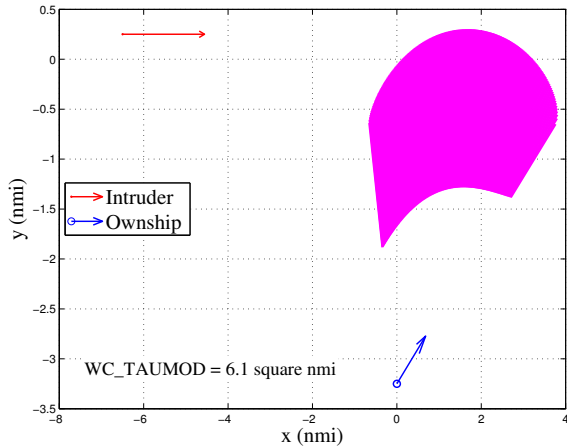
- ▶ DAIDALUS is a reference implementation (Java, C++, and PVS) of a detect and avoid (DAA) concept for Unmanned Aircraft Systems.
- ▶ At the core of the DAA concept, there is a mathematical definition of the **well-clear** concept.
- ▶ DAIDALUS provides algorithms for
 - ▶ Checking well clear (1×1)
 - ▶ Predicting loss of well clear (1×1)
 - ▶ Computing alert level (1×1)
 - ▶ Computing conflict and recovery bands ($1 \times n$)

Well Clear

- ▶ Two aircraft are *well clear* if appropriate distance and time variables determined by their states remain outside a set of predefined threshold values.
- ▶ A well-clear violation occurs when:
 - ▶ range is less than DMOD **or** (distance at time of CPA is less than HMD **and** modified tau is less than TAUMOD) **and**
 - ▶ relative altitude is less than ZTHR **or** time to co-altitude is less than TCOA.
- ▶ Concrete values for threshold values is matter of research.
SARP recommendation: $HMD = DMOD = 4000 \text{ ft}$,
 $TAUMOD = 35 \text{ s}$, $ZTHR = 450 \text{ ft}$, and $TCOA = 0 \text{ s}$.

Well-Clear Violation Volume

Top View of an Example Encounter



Well-Clear Properties

- ▶ **Inclusion**: For an appropriate choice of parameters, the well-clear violation volume is larger than the TCAS volume.
- ▶ **Symmetry**: In a pair-wise situation, both aircraft make the same determination about their well-clear status.
- ▶ **Local Convexity**: In a non-maneuvering trajectory, there is at most one time interval where the aircraft are in well-clear violation.

Well-Clear Algorithms: Time To Violation

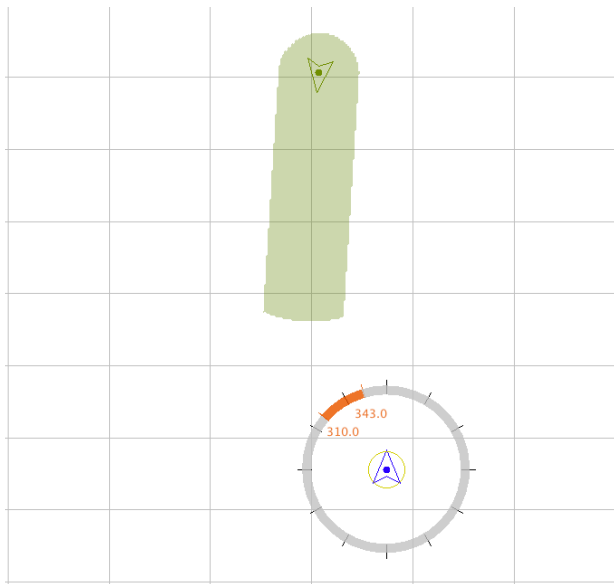
- ▶ Given ownship and intruder state information and a lookahead time, return time interval of well-clear violation assuming non-maneuvering trajectories.
- ▶ Return empty interval when aircraft are not predicted to be in well-clear violation within the lookahead time.
- ▶ Return an interval that contains 0 (current time) when aircraft are currently in well-clear violation.

Well-Clear Algorithms: Conflict Bands

- ▶ Given ownship and traffic state information and a lookahead time, compute ranges of *track*, *ground speed*, *vertical speed*, and *altitude* that lead to well-clear violation within lookahead time. . .
- ▶ . . . assuming a kinematic trajectory for the ownship and non-maneuvering trajectories for the traffic aircraft.

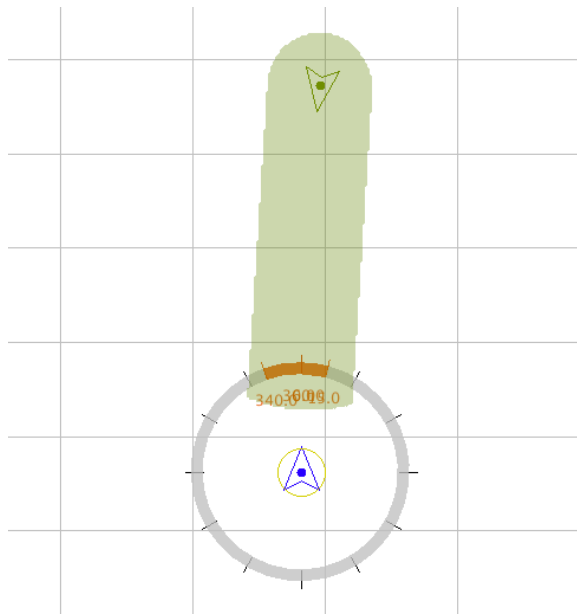
Preventive Bands

Bands outside current trajectory of the aircraft:



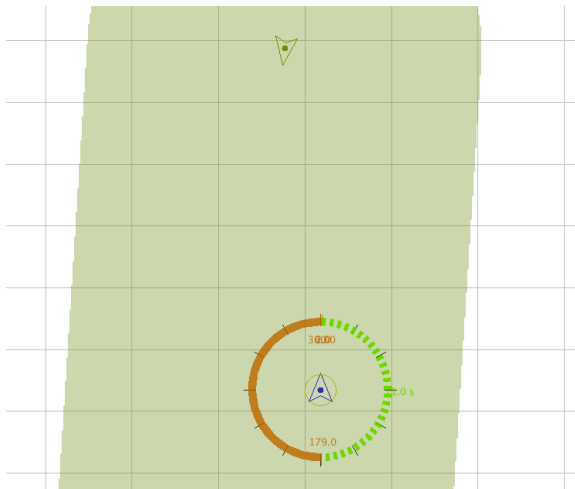
Corrective Bands

Bands in current trajectory of the aircraft:



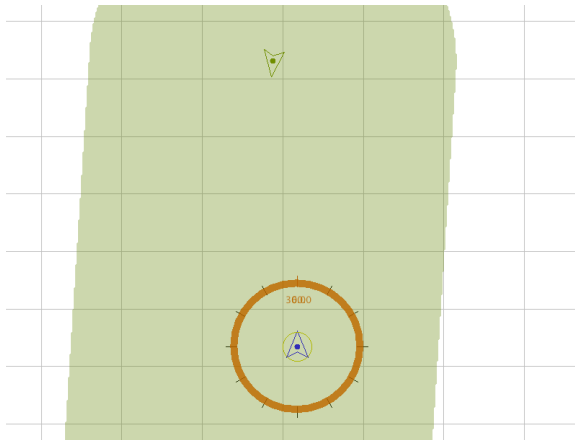
Recovery Bands

Aircraft are (about to be) in well-clear violation:



Full Red

Aircraft are within DMOD and ZTHR distance:








Well-Clear Algorithms: Alerting Logic

- ▶ Given ownship and intruder state information, return an alert level (from 0 to 4) indicating severity of potential loss of well clear.
- ▶ Two alerting schemas are supported:
 - ▶ Thresholds-based.
 - ▶ Bands-based.

Thresholds-Based Alerting Logic






- ▶ Alert levels correspond to predicted violation with respect to different sets of threshold values. The smaller the values, the greater the severity level.
- ▶ Logic: For a given intruder, return most severe alert type for which Time To Violation is less than Alerting Time.

Type	Symbol	Threshold Values ³	Alerting Time
4		HMD=0.75 nm, ZTHR=450 ft	25 s
3		HMD=0.75 nm, ZTHR=450 ft	75 s
2		HMD=1.0 nm, ZTHR=700 ft	75 s
1		HMD=1.5 nm, ZTHR=1200 ft	85 s
0		—	—

³TAUMOD=35 s and TCOA=0 s.

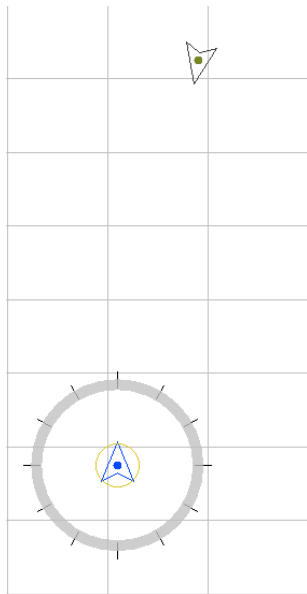
Bands-Based Alerting Logic

- ▶ Alert levels correspond to types of bands, i.e., no bands, preventive, corrective, and recovery.
- ▶ Logic: For a given intruder, return alert type corresponding to type of bands contributed by that aircraft.

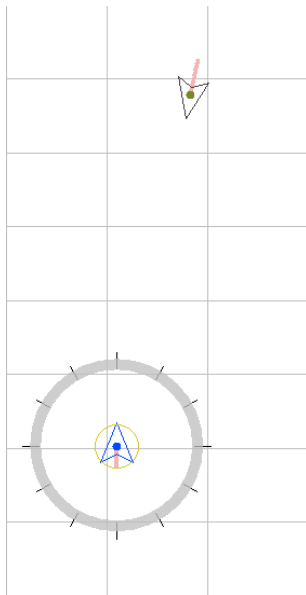
Type	Symbol	Bands ⁴
4		Full Red
3		Recovery
2		Corrective
1		Preventive
0		None

⁴HMD=0.65 nm, ZTHR=450 ft, TAUMOD=35 s. TCOA and Alerting Time are matter of research.

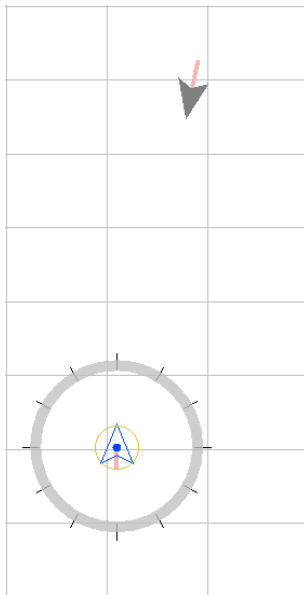
Time 0



Bands-based

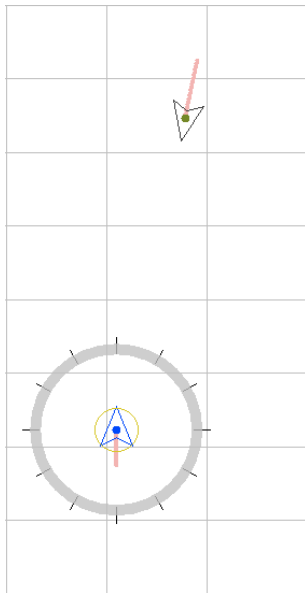


Thresholds-based

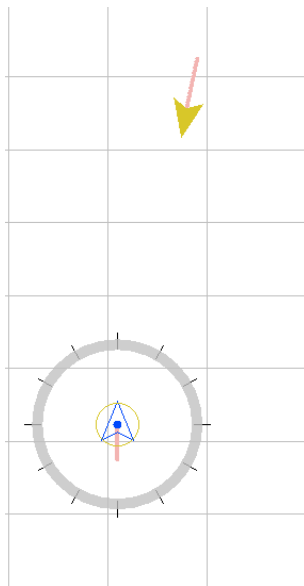


Time 34s

Bands-based

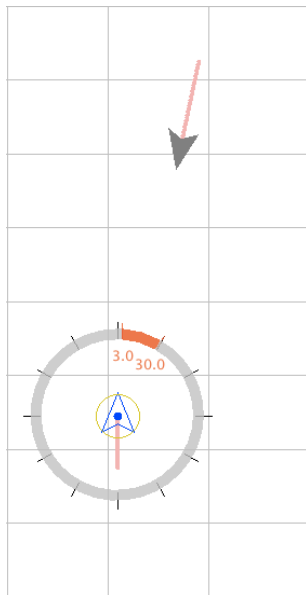


Thresholds-based

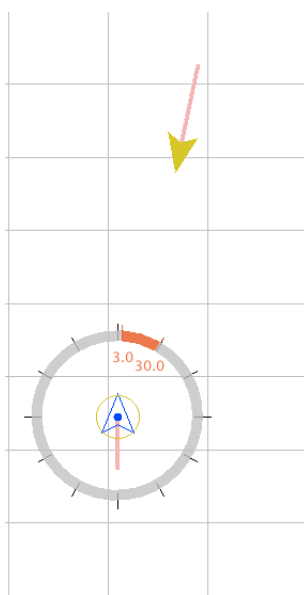


Time 50s

Bands-based

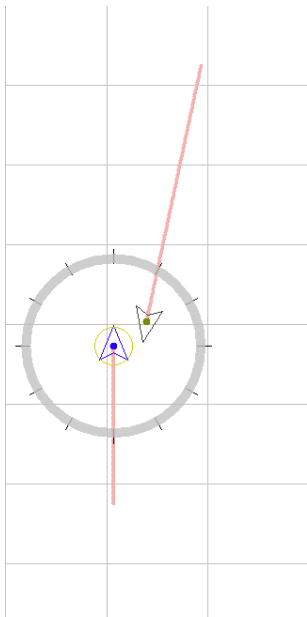


Thresholds-based

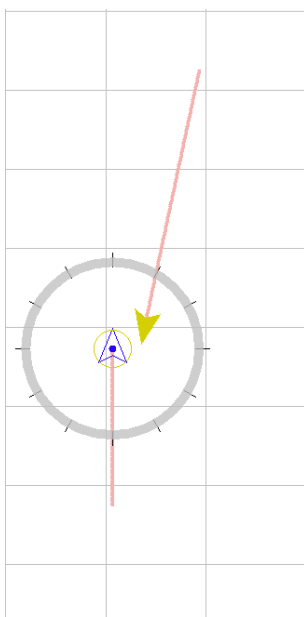


Time 140s

Bands-based

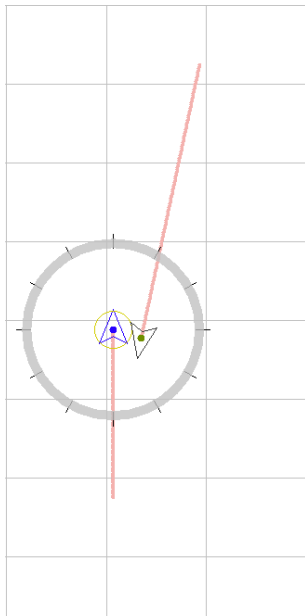


Thresholds-based

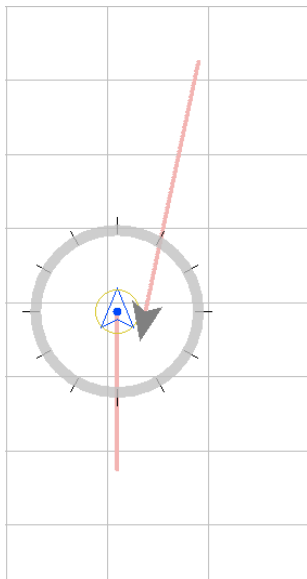


Time 151s

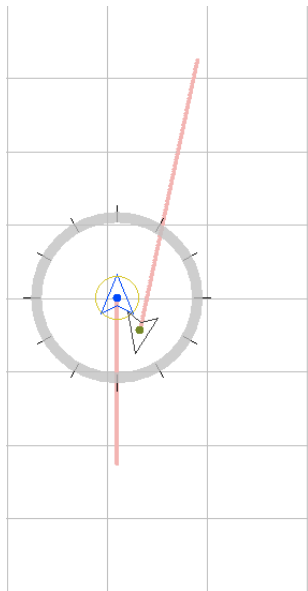
Bands-based



Thresholds-based



Time 160s



Current Status

- ▶ Formal specification and verification of algorithms in the Prototype Verification System (PVS): **done**.
- ▶ Prototype code in Java and C++: **mostly done**.
- ▶ Software verification: **in progress**.

References (I)

- ▶ C. Muñoz, A. Narkawicz, G. Hagen, J. Upchurch, A. Dutle and M. Consiglio, *Detect & Avoid Alerting Logic for Unmanned Systems (DAIDALUS)*, submitted 2015.
- ▶ J. Upchurch, C. Muñoz, A. Narkawicz, M. Consiglio, and J. Chamberlain, and M. Consiglio, *Characterizing the Effects of a Vertical Time Threshold for a Class of Well-Clear Definitions*, submitted, 2015.
- ▶ J. Upchurch, C. Muñoz, A. Narkawicz, J. Chamberlain, and M. Consiglio, *Analysis of Well-Clear Boundary Models for the Integration of UAS in the NAS*, Technical Memorandum, NASA/TM-2014-218280, June 2014.
- ▶ C. Muñoz, A. Narkawicz, J. Chamberlain, M. Consiglio, and J. Upchurch, *A Family of Well-Clear Boundary Models for the Integration of UAS in the NAS*, Proceedings of the 14th AIAA Aviation Technology, Integration, and Operations (ATIO) Conference, AIAA-2014-2412, Atlanta, Georgia, 2014.

References (II)

- ▶ A. Narkawicz, C. Muñoz, J. Upchurch, J. Chamberlain, and M. Consiglio, *A Well-Clear Volume Based on Time to Entry Point*, Technical Memorandum, NASA/TM-2014-218155, January 2014
- ▶ C. Muñoz, A. Narkawicz, and J. Chamberlain, *A TCAS-II Resolution Advisory Algorithm*, Proceedings of the AIAA Guidance, Navigation, and Control Conference (GNC), AIAA-2013-4622, Boston, Massachusetts, August 2013.
- ▶ M. Consiglio, J. Chamberlain, C. Muñoz, and K. Hoffer, *Concept of integration for UAS operations in the NAS*, Proceedings of the 28th International Congress of the Aeronautical Sciences (ICAS 2012), 2012.

Software Releases Under NASA's Open Source Agreement

- ▶ ACCoRD \subseteq Bands \subseteq Chorus \subseteq Stratway:
<http://shemesh.larc.nasa.gov/fm/fm-at-codes.html>.
- ▶ Well-Clear: <http://github.com/nasa/WellClear>.
- ▶ DAIDALUS \subseteq Stratway \cup Well-Clear.